

Statistical Decision Theory and Bayesian Analysis

CH2. UTILITY AND LOSS

§ 2.2 Utility Theory

- Reward $r \in \mathcal{R}$ "a consequence"

P : a probability distribution over r caused by an action a . caused by
expected utility

$U(r)$: a utility function (satisfying $E^P[U(r)]$ exists)

- "Rationality axioms"

P_2 is preferred P_1, P_2 equivalent

Axiom 1. If $P_1, P_2 \in \mathcal{P}$, then either $P_1 < P_2$, $P_1 \sim P_2$, $P_2 < P_1$

Axiom 2. If $P_1 \leq P_2$ and $P_2 \leq P_3$, then $P_1 \leq P_3$

Axiom 3. If $P_1 < P_2$ then $\alpha P_1 + (1-\alpha)P_3 < \alpha P_2 + (1-\alpha)P_3$
 $\forall \alpha \in (0, 1)$ and $P_3 \in \mathcal{P}$
conditionality principle

Axiom 4. If $P_1 < P_2 < P_3$, there are numbers $0 < \alpha < 1$, and $0 < \beta < 1$ such that

$$\alpha P_1 + (1-\alpha)P_3 < P_2$$

$$\text{and } P_2 < \beta P_1 + (1-\beta)P_3$$



"No heaven or hell"

If P_1 is infinitely bad (i.e. $E^{P_1}[U(r)] = -\infty$)

$\Rightarrow \exists \beta > 0$ s.t. $P_2 < \beta P_1 + (1-\beta)P_3$.

That is to say, U must be bounded

Axioms 1 ~ 5 \Rightarrow a unique utility function (for a particular scale)



However, determining U is difficult.

- Values of consequences may not have obvious scale (e.g. prestige, reputation, etc)
- Utility \neq "True value"

• Construction of U

STEP 1: Consider $r_1 \neq r_2$. Assume $r_1 < r_2$. Then let

$$U(r_1) = 0 \quad U(r_2) = 1$$

Choose r_2 as the best reward and r_1 worst for convenience. But any choice is acceptable

STEP 2: For r_3 s.t. $r_1 < r_3 < r_2$ one-point distribution find the α ($0 < \alpha < 1$)
 s.t. $r_3 \approx p \triangleq \alpha \langle r_1 \rangle + (1-\alpha) \langle r_2 \rangle$

$$U(r_3) = E[U(r)] = \alpha U(r_1) + (1-\alpha) U(r_2) = 1-\alpha$$

STEP 3: For r_3 s.t. $r_3 < r_1 < r_2$. find the α ($0 < \alpha < 1$).
 s.t.
 $r_1 \approx p \triangleq \alpha \langle r_3 \rangle + (1-\alpha) \langle r_2 \rangle$

STEP 4: For r_3 s.t. $r_1 < r_2 < r_3$. find the α ($0 < \alpha < 1$)
 s.t.
 $r_2 \approx p \triangleq \alpha \langle r_1 \rangle + (1-\alpha) \langle r_3 \rangle$

Then

$$1 = U(r_2) = E[U(r)] = \alpha U(r_1) + (1-\alpha) U(r_3) = (1-\alpha) U(r_3)$$

$$\Rightarrow U(r_3) = \frac{1}{1-\alpha}$$

STEP 5: Periodically check the construction process for consistency by comparing new combinations of rewards.

Assume $r_3 < r_4 < r_5$ found by STEP 1-4. Then find α .

$$r_4 \approx p \triangleq \alpha \langle r_3 \rangle + (1-\alpha) U(r_5)$$

make sure

$$U(r_4) = \alpha U(r_3) + (1-\alpha) U(r_5)$$

We find defined α
 s.t. $U(r_4) = \alpha U(r_3) + (1-\alpha) U(r_5)$

- Notes:
1. This process of comparing and recomparing it often how the best judgement can be made. But that may not reflect real preference over
 2. People do not intuitively tend to act in accordance with a utility function. Thus we are, in essence, r_3, r_4, r_5 . defining rational behavior for an individual, and suggesting that such behavior is good.

Example a_1 : football a_2 : movie

rain (θ_1)	$r_1 = (a_1, \theta_1)$ 0	$r_3 = (a_2, \theta_1)$ 0.3	$\pi(\theta_1) = 0.4$
no rain (θ_2)	$r_2 = (a_1, \theta_2)$ 0.6	$r_4 = (a_2, \theta_2)$ 0.6	$\pi(\theta_2) = 0.6$

Determine r_1, r_2, r_3, r_4 and take an action.

It is obvious that

$$r_1 < r_4 < r_3 < r_2$$

assume we prefer football

- We assign $U(r_1) = 0$ $U(r_2) = 1$
- Gamble r_4 against $\alpha \langle r_1 \rangle + (1-\alpha) \langle r_2 \rangle$ until we feel equally happy.

After some soul searching, we decide $\alpha = 0.4$. i.e.

$$r_4 \approx 0.4 \langle r_1 \rangle + (1-\alpha) \langle r_2 \rangle$$

$$U(r_4) = 0.6$$

- Gamble r_3 against $\alpha \langle r_1 \rangle + (1-\alpha) \langle r_2 \rangle$, we decide $\alpha = 0.3$

$$r_3 \approx 0.3 \langle r_1 \rangle + 0.7 \langle r_2 \rangle, \quad U(r_3) = 0.7$$

- Check consistency:

$$r_3 \approx \alpha \langle r_4 \rangle + (1-\alpha) \langle r_2 \rangle, \text{ what is } \alpha?$$

Then we feel α should be 0.6

$$0.6 = U(r_3) = \alpha U(r_4) + (1-\alpha) U(r_2) = 0.6 \cdot 0.6 + (1-0.6) \cdot 1 = 0.76$$

↓ contradiction

- Re-examine by introspection again until utilities are consistent.

$$\text{Say } U(r_4) = 0.6 \quad U(r_3) = 0.75$$

- Watching football $E^{\pi_{a_1}}[U(r)] = \pi(\theta_1) \cdot U(r_1) + \pi(\theta_2) \cdot U(r_2) = 0.4 \cdot 0 + 0.6 \cdot 1 = 0.6$

$$\text{Watching a movie } E^{\pi_{a_2}}[U(r)] = \pi(\theta_1) \cdot U(r_3) + \pi(\theta_2) \cdot U(r_4) = 0.4 \cdot 0.75 + 0.6 \cdot 0.6 = 0.66$$

⇒ The optimal action is go to the movie.

- Dealing with large \mathcal{R}

- Estimate at a few points and then interpolate
- High dimensional \mathcal{R} : regression

E.g. $U(r) = \sum_{i=1}^m K_i U_i(r_i)$ (Naive Bayes assumption)

$$U(r) = \sum_{i=1}^m K_i U_i(r_i) \prod_{j=1}^m K_{ij} U_j(r_j)$$

(Two side effects of a drug might be acceptable separately, but very dangerous if they occur together)

§ 2.3

- The Utility of Money

"backward binary construction"

1° Choose $r_1 < r_2$ and set $U(r_1) = 0$ and $U(r_2) = 1$

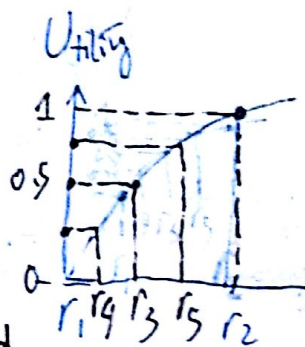
2° Find $r_3 \approx \frac{1}{2} U(r_1) + \frac{1}{2} U(r_2)$, indicating

$$U(r_3) = \frac{1}{2} U(r_1) + \frac{1}{2} U(r_2) = \frac{1}{2}$$

3° Find $r_4 \approx \frac{1}{2} \langle r_1 \rangle + \frac{1}{2} \langle r_3 \rangle$ and $r_5 \approx \frac{1}{2} \langle r_3 \rangle + \frac{1}{2} \langle r_2 \rangle$

$$U(r_4) = \frac{1}{4} \quad U(r_5) = \frac{3}{4}$$

4° Is $r_3 = \frac{1}{2} \langle r_4 \rangle + \frac{1}{2} \langle r_5 \rangle$ acceptable?



Petersburg paradox

Gamble at cost c , A fair win is flipped until a tail first appears.

Reward: $\$2^n$ where n is the number of flips it takes until a tail appears.

Expected gain (in money): $\sum_{n=1}^{\infty} 2^n P(n \text{ flips}) = \sum_{n=1}^{\infty} 2^n \cdot \frac{1}{2^n} = \infty$

Expected utility (for change) $\sum_{n=1}^{\infty} U(2^n - c) \cdot 2^{-n}$

Either positive or negative depending on c .

§ 2.4 The Loss Function

- Loss functions should be defined on utilities.

However, utilities are usually not linear

Example: A coin is flipped n times.

$$p(\text{Head}) = 0.6 \Rightarrow \text{win } \$10,000$$

$$p(\text{Tail}) = 0.4 \Rightarrow \text{lose } \$1,000$$

Let Z_i denote the amount won on the i -th flip.

Assume
$$U(r) = \begin{cases} r^{1/3} & \text{if } r \geq 0 \\ 2r^{2/3} & \text{if } r < 0 \end{cases}$$

$$\begin{aligned} E[U(Z_i)] &= 0.6 \cdot U(1000) + 0.4 \cdot U(-1000) \\ &= 0.6 \cdot 10 + 0.4 \cdot (-20) \\ &= -2 \end{aligned}$$

However $\sum_{i=1}^n E[U(Z_i)] \neq -2n$ if $i \neq 1$.

In fact the true outcome $Z = \sum_{i=1}^n Z_i$ can be positive

- Standard Loss Function: Squared-Error Loss

X Cons: Unbounded, convex. ↖ an estimator of θ

✓ Pros: Assume $Z = h(\theta - a, Y)$ ↖ Some randomness other than θ . (also independent of θ)

✓ Another merit:
For an estimator $\hat{\theta}$
 $R(\theta, \hat{\theta}) = E_{\theta}^X [L(\theta, \hat{\theta})]$
 $= E_{\theta}^X [L(\theta - \hat{\theta}(X))]^2$
 R happens to be the variance of $\hat{\theta}$, if $\hat{\theta}$ unbiased

$$g(\theta - a, Y) \triangleq U(h(\theta - a, Y))$$

Taylor expansion, assume $\theta - a$ is small derivatives wrt. $\theta - a$

$$g(\theta - a, Y) \approx g(0, Y) + (\theta - a) g'(0, Y) + \frac{1}{2} (\theta - a)^2 g''(0, Y)$$

Denote $K_1 = -E^Y [g'(0, Y)]$, $K_2 = -E^Y [g''(0, Y)]$ and $K_3 = \frac{1}{2} E^Y [g'''(0, Y)]$
↖ Y is the only thing random in Z .

Then $L(\theta, a) \approx$

$$= -E[U(Z)] \approx K_1 + K_2(\theta - a) + K_3(\theta - a)^2$$

$$\Rightarrow L(\theta-a) \approx k_3 \left(\theta - a + \frac{k_2}{2k_3} \right)^2 + \left(k_1 - \frac{k_2^2}{4k_3} \right)$$

Provided $k_3 > 0$, $k_2 = 0$ (if $g(\theta, y)$ symmetric in y and Y is symmetric distribution)

and $\theta \approx a$, ~~then~~ the loss is then squared error.

- Variants:
- $L(\theta, a) = (\theta - a + c)^2$
 - Weighted squared error.

$$L(\theta, a) = w(\theta) \cdot (\theta - a)^2$$

- Quadratic loss

$$L(\theta, a) = (\theta - a)^T Q (\theta - a)$$

If diagonal

$$L(\theta, a) = \sum_{i=1}^p q_i (\theta_i - a_i)^2$$

• Standard Loss Function: Linear Loss

$$L(\theta, a) = \begin{cases} k_0(\theta - a) & \text{if } \theta - a \geq 0 \\ k_1(a - \theta) & \text{if } \theta - a < 0 \end{cases}$$

or $L(\theta, a) = |\theta - a|$

or weighted linear loss

• Standard Loss Function: "0-1" Loss

$$L(\theta, a_i) = \begin{cases} 0, & \text{if } \theta \in \Theta_i \\ 1, & \text{if } \theta \in \Theta_j \quad j \neq i \end{cases}$$

Risk: $R(\theta, \delta) = E_{\theta}^X [L(\theta, \delta(X))] = P_{\theta} \{ \delta(X) \text{ incorrect} \}$ error, depending on $\theta \in \Theta_0$ or $\theta \in \Theta_1$

Bayesian expected loss:

$$P(\pi^*, a_i) = \int L(\theta, a_i) dF^{\pi^*}(\theta) = 1 - p^{\pi^*}(\theta \in \Theta_i)$$

Either type I or II

More realistic approximations

$$L(\theta, a_i) = \begin{cases} 0, & \text{if } \theta \in \Theta_i \\ k_i, & \text{if } \theta \in \Theta_j \quad (i \neq j) \end{cases} \quad \text{or} \quad L(\theta, a_i) = \begin{cases} 0 & \text{if } \theta \in \Theta_i \\ k_i(\theta) & \text{if } \theta \in \Theta_j \quad (i \neq j) \end{cases}$$

• For Inference Problems

Example. Let C denotes a confidence rule, $C(x)$ being a confidence set.

$$\text{Define } L(\theta, C(x)) = 1 - I_{C(x)}(\theta) = \begin{cases} 1 & \text{if } \theta \notin C(x) \\ 0 & \text{if } \theta \in C(x) \end{cases}$$

$$\text{Then } R(\theta, C) = \mathbb{E}_\theta [1 - I_{C(x)}(\theta)] = 1 - P_\theta \{ C(x) \text{ contains } \theta \}$$

$$P(\pi^*, C(x)) = \mathbb{E}^{\pi^*} [1 - I_{C(x)}(\theta)] = 1 - P^{\pi^*}(\theta \in C(x))$$

Example. Measuring the "communication quantity"

Consider the example on p. 4. (SDT/BA-CH1).

where $X = (X_1, X_2)$ X_i iid. $P_\theta(X_i = \theta - 1) = P_\theta(X_i = \theta + 1) = \frac{1}{2}$

Frequentist confidence $\alpha_1(x) \equiv .75$

Conditionalist confidence $\alpha_2(x) = \begin{cases} 1 & \text{if } x_1 \neq x_2 \\ 0.5 & \text{if } x_1 = x_2 \end{cases}$

Define $L_C(\theta, \alpha(x)) = (I_{C(x)}(\theta) - \alpha(x))^2$

$$R_C(\theta, \alpha_1) = \mathbb{E}_\theta^X L_C(\theta, \alpha_1(x)) = \frac{3}{16}$$

$$R_C(\theta, \alpha_2) = \mathbb{E}_\theta^X L_C(\theta, \alpha_2(x)) = \frac{1}{8}$$

- For Predictive Problems

To predict $Z \sim g(z|\theta)$

$$\therefore \text{Then } L(\theta, a) = \mathbb{E}_{\theta}^Z[L^*(z, a)] = \int L^*(z, a) g(z|\theta) dz$$

Example: $Z \sim \mathcal{N}(\theta, \sigma^2)$ Let $L^*(z, a) = (z-a)^2$

$$\begin{aligned} L(\theta, a) &= \mathbb{E}_{\theta}^Z [z-a]^2 = \mathbb{E}_{\theta}^Z [z-\theta + \theta-a]^2 \\ &= \mathbb{E}_{\theta}^Z [z-\theta]^2 + \mathbb{E}_{\theta}^Z [\theta-a]^2 = \sigma^2 + (\theta-a)^2 \end{aligned}$$

\Rightarrow Working with $L(\theta, a) \Leftrightarrow$ working with squared-error loss for θ